

## APPLICATIONS OF SHAPE OPTIMIZATION WITH LS-OPT AND ANSA

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KEYWORDS - Optimization, Morphing, META-Models, Crashworthiness, Process Flow

ABSTRACT - The purpose of this paper is to explore aspects of shape and geometry optimization for nonlinear applications and to propose optimization strategies for such problems.

Different optimization strategies are discussed and pros and cons are compared. The application of the Successive Response Surface Method (SRSM) for optimization of nonlinear applications is demonstrated. This is performed using LS-OPT as optimization software and ANSA as pre-processor for geometry variation. For this ANSA is run in batch mode and is driven by parameterized control files, which interface with the optimization software LS-OPT. By the variation of morphing control parameters or just geometrical translational or rotational operations the design is optimized with respect to shape properties and geometrical configuration. After morphing operations usually automated batch meshing of the considered parts is applied.

The set-up of the process flow and how the several programs interface with each other is also described in the paper.

In addition, a methodology to get a reliable surrogate model using neural networks is introduced. The surrogate model (META-Model or Response Surface Model) approximates the relationship between design parameters and a simulation response and can be used to visualize and explore the design space.

One of the regarded examples treats the optimization of a crash box at AUDI. The procedure of generating an advanced  $\mu$ ETA-model to get an approximation of the global design space using neural networks is demonstrated for this example. Furthermore, the visualization of multi-dimensional meta-models in two- and three-dimensional design space is illustrated by using the software D-SPEX. The program D-SPEX interfaces with LS-OPT as an advanced optimization and stochastic post-processor.



## Applications of Shape Optimization with LS-OPT and ANSA



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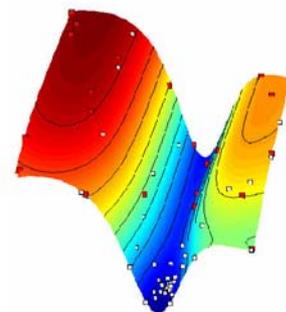
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### → Overview

- Introduction
- Methodologies for Optimization in LS-OPT
- Example I
  - Optimization of a Crash Box
  - Conclusions
- Example II
  - Sensitivity Study (DOE) for Radiation Analysis
  - Conclusions



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**Introduction**

- Introduction
- Methods – Optimization
- Example I – Crash
- Conclusions
- Example II - Radiation
- Conclusions

**→ About DYNAmore**

- Distributor of LS-DYNA and related software products in Germany, Austria, Switzerland and other european countries
- Further development and customization in collaboration with LSTC (long term relationship)
- DYNAmore in total 34 People (June 2007)
- LS-DYNA Software Models
  - Many Dummy Models
  - Barrier Models
  - Pedestrian Safety Models
  - Human Models (Thums)

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**Introduction**

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**→ Optimization Competence Center at DYNAmore**

- Many experience particularly in crashworthiness optimization, reliability and robustness studies, MDO, Meta-Modelling...
- Main optimization customers

Karmann

DOW Automotive

**software**

- LS-OPT (LSTC)
- Vanderplaats (VR&D) optimization products
- D-SPEX

**engineering**

- optimization engineering services
- consulting
- benchmarks

**seminars**

- several training classes
  - optimization
  - robustness/reliability
  - parameter ident.
- informational events

**services**

- support (phone, on-site)
- software development
- system integration and process flow

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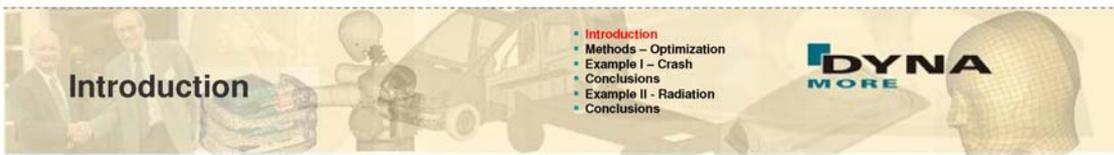
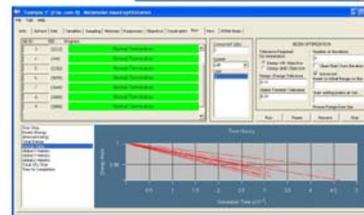
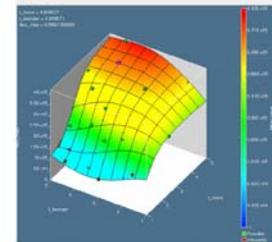


➔ About LS-OPT

- LS-OPT is a **product of LSTC** (Livermore Software Technology Corporation)
- LS-OPT can be linked to any **simulation code** – stand alone optimization software

■ Methodologies/Features:

- Successive Response Surface Method (SRSM)
- Reliability based design optimization (RBDO)
- Multidisciplinary optimization (MDO)
- Multi-Objective optimization (Pareto)
- Discrete Optimization
- numerical/analytical based sensitivities
- Analysis of Variance (ANOVA)
- Stochastic/Probabilistic Analysis
- Monte Carlo Analysis using Metamodels
- ...



➔ About LS-OPT

■ Job Distribution - Interface to Queuing Systems

- PBS, LSF, LoadLeveler, AQS, etc.

■ LS-OPT might be used as a “Process Manager”

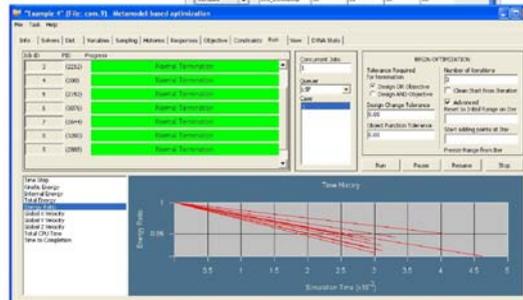
■ Shape Optimization

- Interface to SFE-Concept, Hypermesh ANSA, DEP-Morpher
- User-defined interface to any Pre-Processor

■ Parameter Identification Module

■ Visualization of Statistical Quantities on the FE-Model

Type	Name	Starting	Range	Minimum	Maximum
Variable	SHA_VENT	24	20	2.70	24
Variable	PAR_APT1_01a	40	10	10	300
Variable	CUR_POR1a	0.5	1	1	1
Variable	CUR_POR2a	0.5	1	1	1
Variable	PAR_APT1_01b	2.20	1	1	2.5
Variable	PAR_APT1_01c	40	10	10	300
Variable	PAR_APT1_01d	40	10	10	300
Variable	PAR_APT1_01e	40	10	10	300
Variable	PAR_APT1_01f	40	10	10	300
Variable	PAR_APT1_01g	40	10	10	300
Variable	PAR_APT1_01h	40	10	10	300
Variable	PAR_APT1_01i	40	10	10	300
Variable	PAR_APT1_01j	40	10	10	300
Variable	PAR_APT1_01k	40	10	10	300
Variable	PAR_APT1_01l	40	10	10	300

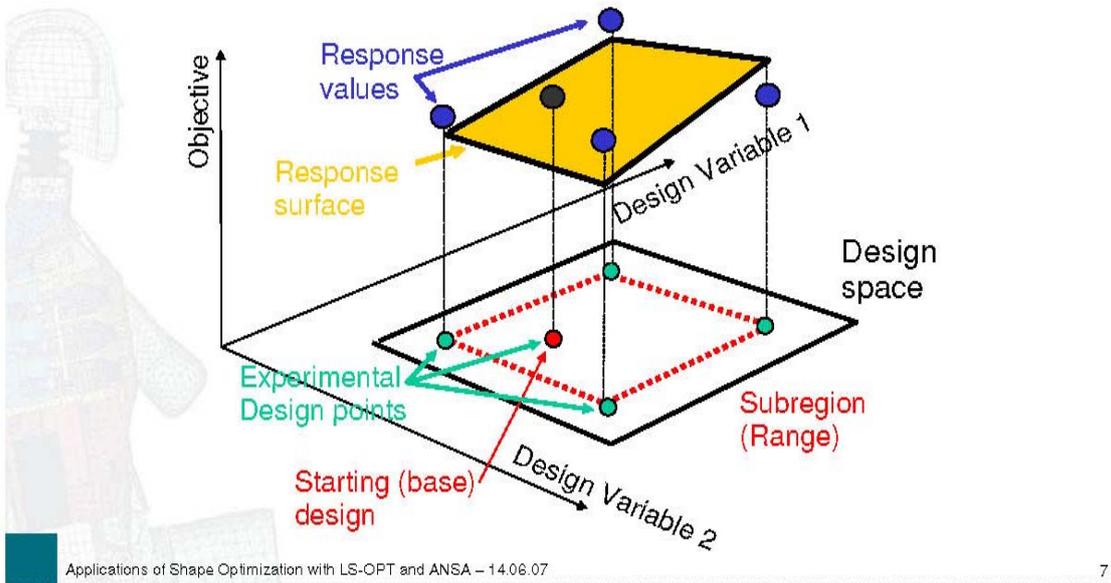


**Methods - Optimization**

- Introduction
- **Methods - Optimization**
- Example I - Crash
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**DYNA MORE**

→ **Response Surface Methodology - Optimization Process**

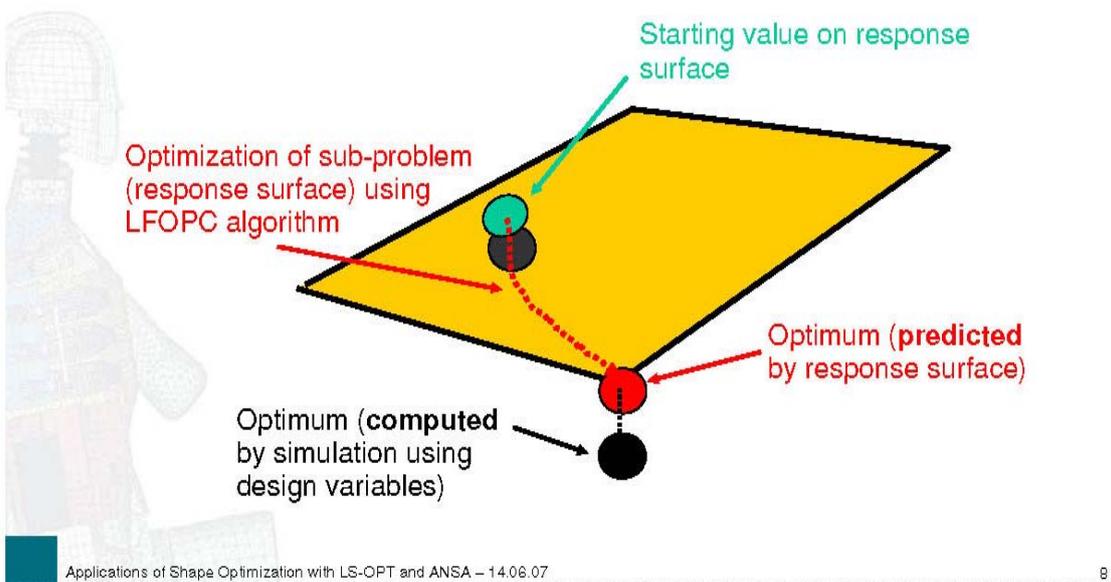


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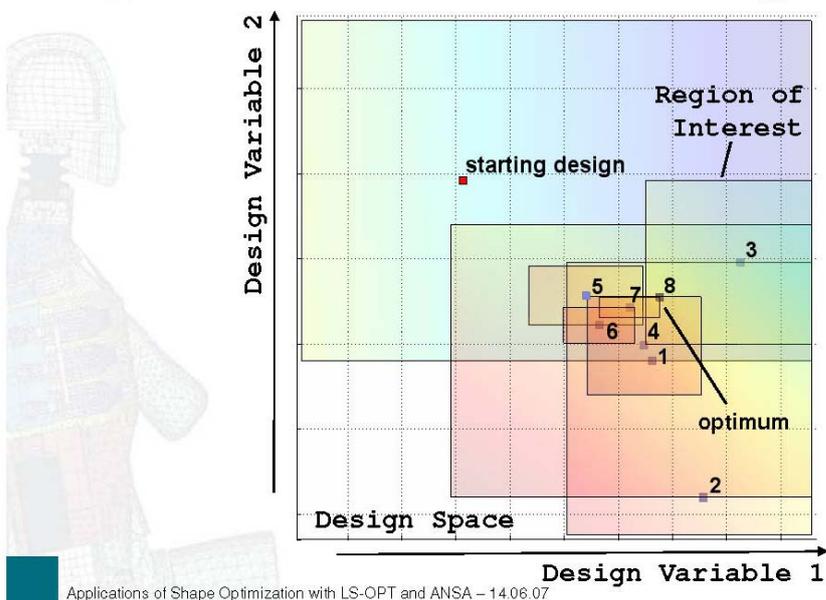
**DYNA MORE**

→ **Find an Optimum on the Response Surface (one iteration)**



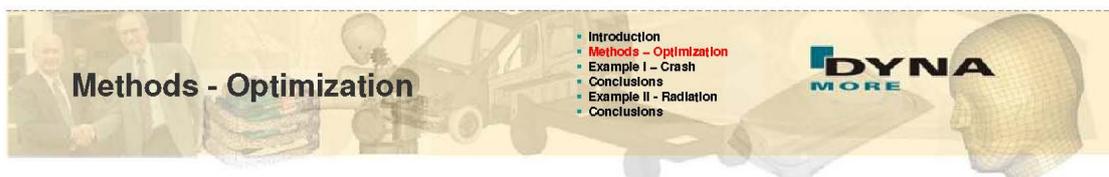


→ **Successive Response Surface Methodology**



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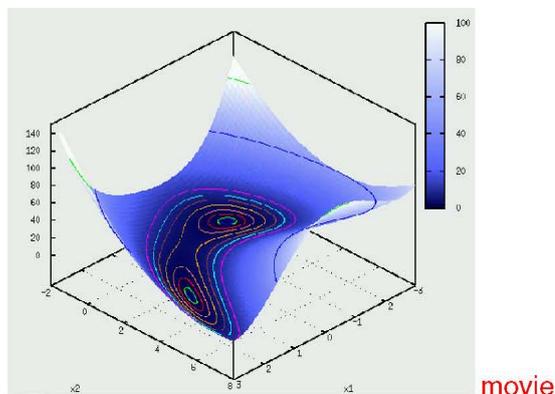
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→ **Successive Response Surface Methodology**

■ Example - 4th order polynomial

$$g(\mathbf{x}) = 4 + \frac{9}{2}x_1 - 4x_2 + x_1^2 + 2x_2^2 - 2x_1x_2 + x_1^4 - 2x_1^2x_2$$



movie

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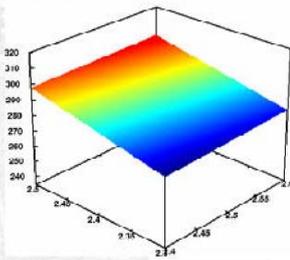
## Methods - Optimization

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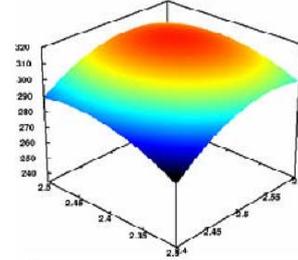


→ **Response Surfaces (Meta Models)**

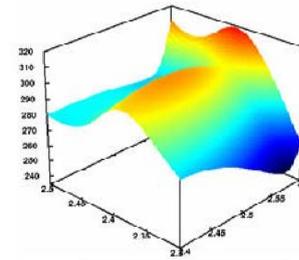
- Linear, Quadratic and Mixed polynomial based
- Neural Network and Kriging for Nonlinear Regression



**linear polynomial**



**quadratic polynomial**



**neural network**

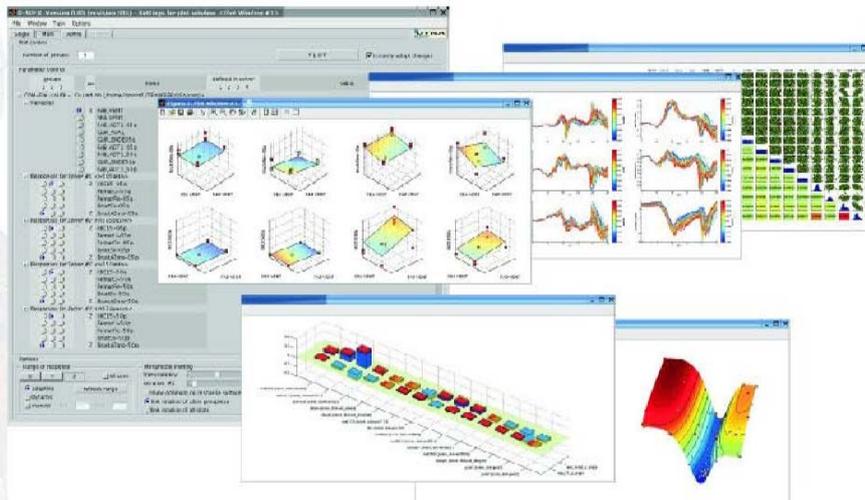
## Exploring Design Space using D-SPEX

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→ **D-SPEX Meta-Model Viewer - Exploration of Design Space**

- Compare response surfaces, curve plots, ant-hill plots, ...

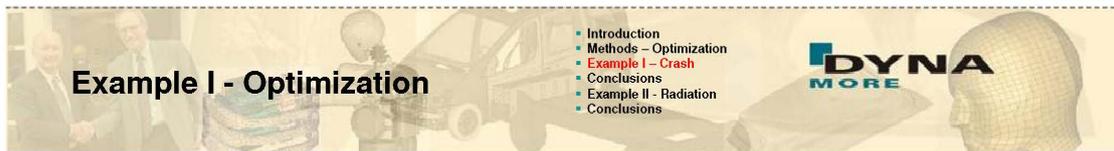
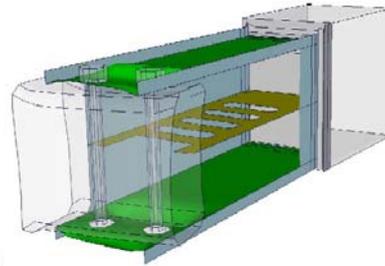




## Example I - Optimization

### → Optimization of a Crash Box

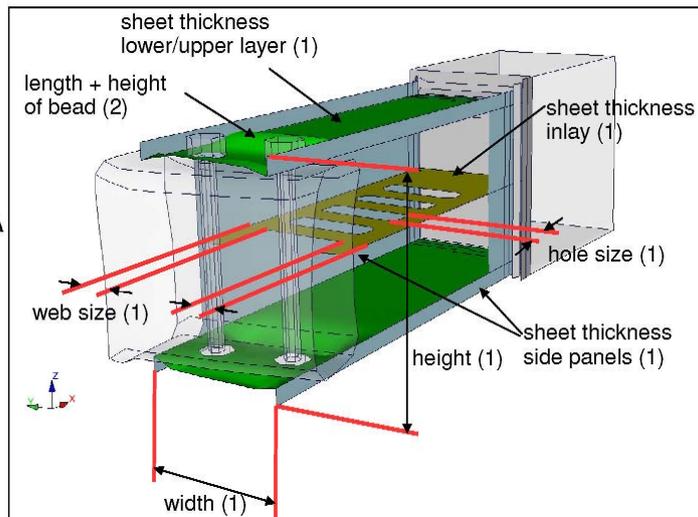
- The objective is to improve the energy absorption of a crash box and to reduce the maximum force level
- **Sheet thickness variables** as well as **geometric variables** are considered
- **Test load is 1 m/s** boundary prescribed motion applied by a rigid wall
- Optimization formulation: a maximum load level (contact force) has not to be exceeded (**constraint**) while a maximum of energy has to be absorbed (**objective**)



## Example I - Optimization

### → Optimization of a Crash Box

- Total 9 design variables
- Use of Successive Response Surface Method with LS-OPT
- Parameterization by Morphing through ANSA
- In total 240 simulations within 15 iterations



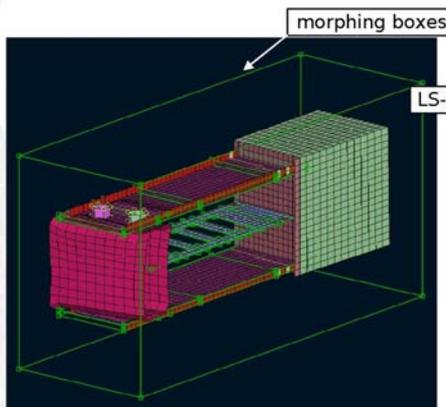
**Example I - Optimization**

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➔ **Morphing with ANSA and LS-OPT**

- ANSA is specified as Pre-Processor in LS-OPT
- Multiple crash simulation input files are generated automatically through ANSA in batch mode



INPUT VARIABLES					
Type	ID	Value	Name		
morph_param	1	<<BREITE>>	Breite_rechts		
morph_param	1	<<BREITE>>	Breite_links		
morph_param	1	<<RUERE>>	Roete_oben		
morph_param	1	<<RUERE>>	Roete_unten		
morph_param	1	<<LAEHGE_STICKE>>	Interfuehliche_Laenge		
morph_param	1	<<RUERE_STICKE>>	Schraufuehliche_Roete_oben		
morph_param	1	<<RUERE_STICKE>>	Schraufuehliche_Roete_unten		
morph_param	1	<<LOCH_BREITE>>	Loch_Breite_rechts		
morph_param	1	<<LOCH_BREITE>>	Loch_Breite_links		
morph_param	1	<<LOCH_LAEHGE>>	Loch_Laenge_rechts		
morph_param	1	<<LOCH_LAEHGE>>	Loch_Laenge_links		
Type	ID	Value	Name		
Connective	100001	6, 50,			
Connective	100002	6, 50,			
Type	ID	Value	Name		
Seitenbleche	123007	<<T_SEITE>>			
thickness	123007	<<T_SEITE>>			
thickness	123011	<<T_SEITE>>			
thickness	123012	<<T_SEITE>>			
Mitteblech	123013	<<T_MITTE>>			
thickness	123013	<<T_MITTE>>			
thickness	123014	<<T_MITTE>>			
Bleche Oben und Unten	123008	<<T_OBERSEITE>>			
thickness	123008	<<T_OBERSEITE>>			
thickness	123012	<<T_OBERSEITE>>			
Type	FID	Target length	min length	max length	angle
FID in Rowset in optimizer_mod.c					
recount	6.7	4	19	15	

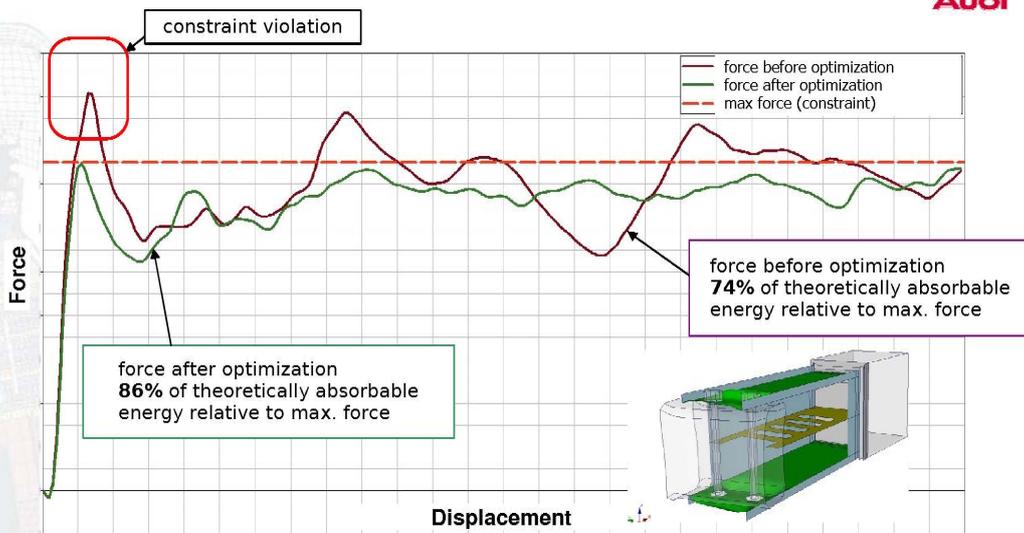
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**Example I - Optimization**

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➔ **Optimization Result**



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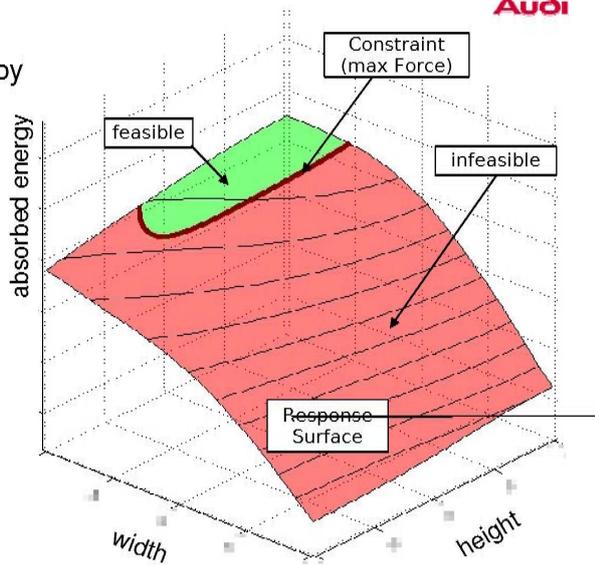
**Example I - Optimization**

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➔ **Design Study using D-SPEX**

- Visualization of the relationship between variables and responses by means of a response surface
- Can give a deeper understanding of the influences of parameters upon the results



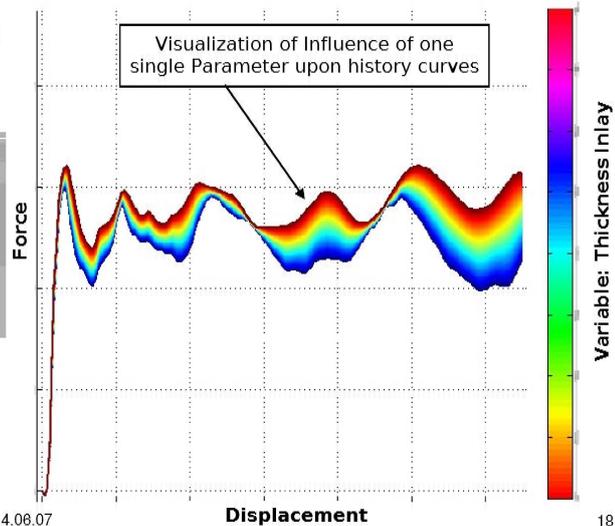
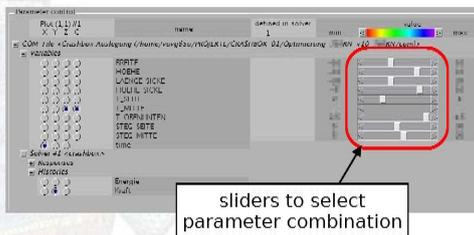
**Example I - Optimization**

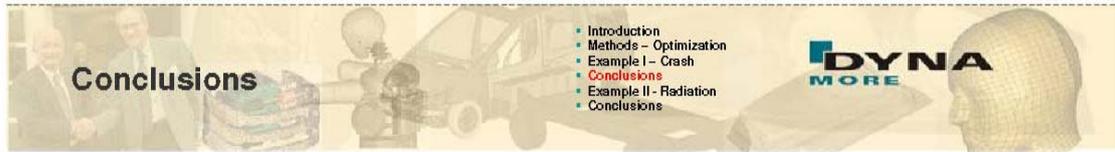
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➔ **Enhanced Visualization of Simulation results using D-SPEX**

- Utilizing response surfaces to approximate curves for specific parameter combination





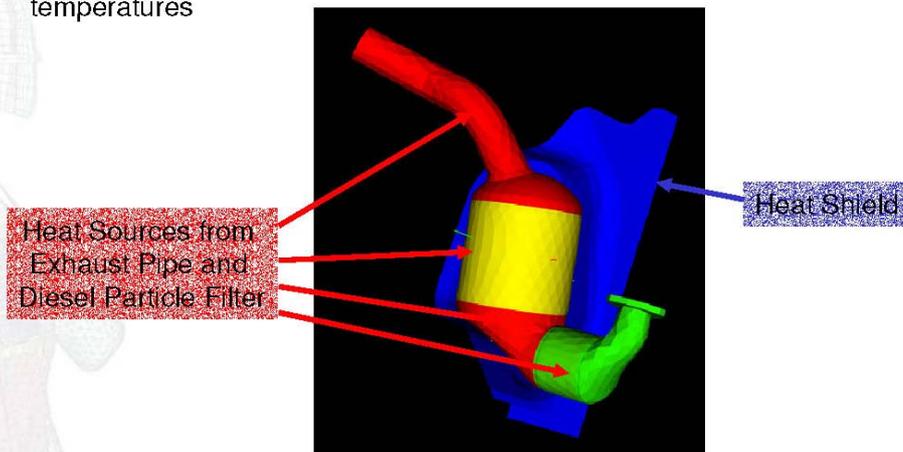
### → Conclusions

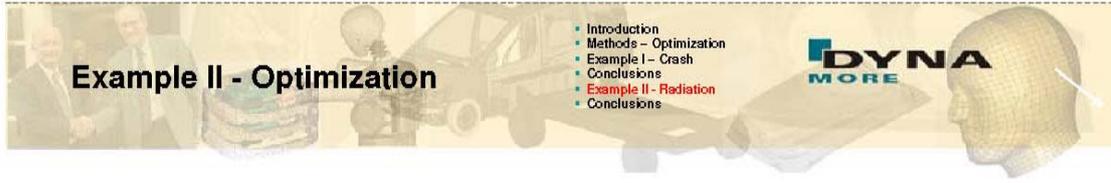
- LS-OPT is a suitable tool for crash box optimization
- Numerical optimization achieved better design and can save manpower in the design process of a crash box
- Morphing capabilities of ANSA are essential in order to realize geometric parameterization
- Visualization of results with D-SPEX can give you a deeper understanding of the influences of parameters upon the results



### → DOE Sensitivity Analysis for Radiation Analysis

- Problem Description: Heat shield to protect environment from high temperatures

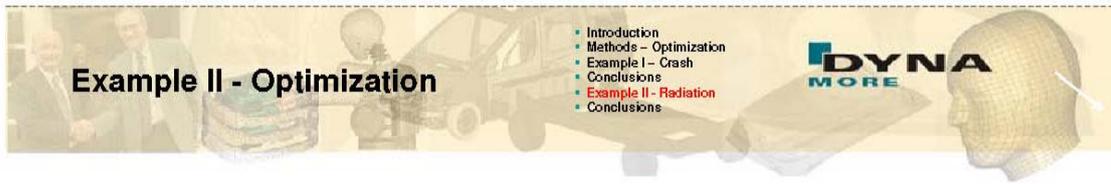
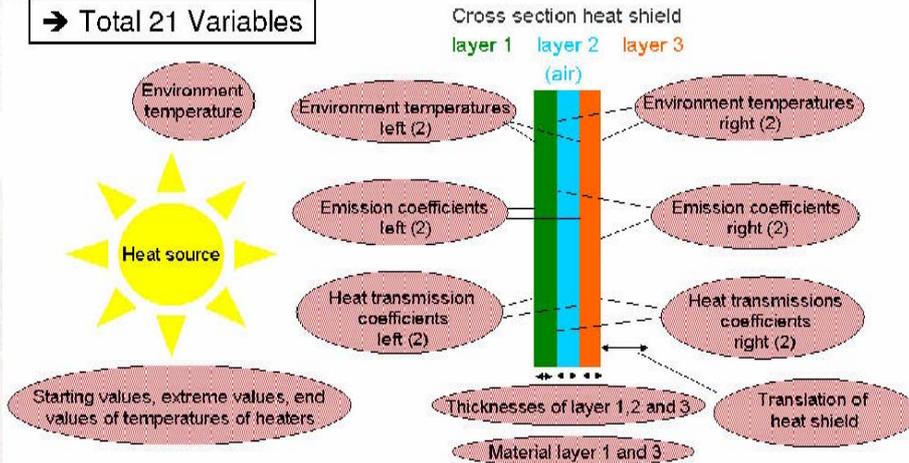




→ DOE Sensitivity Analysis for Radiation Analysis

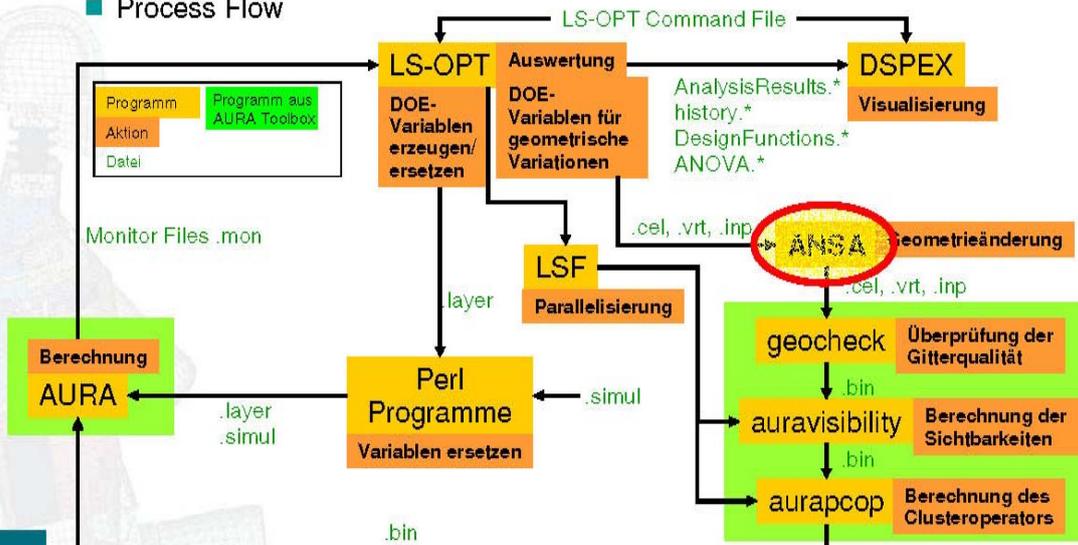
■ Variables considered for DOE

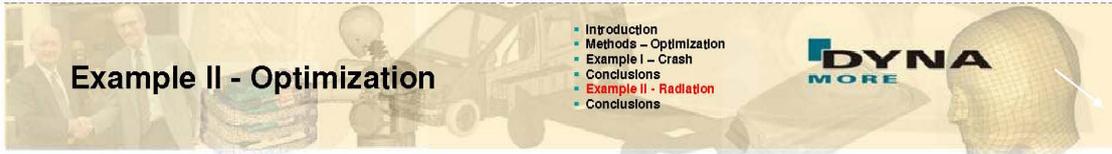
→ Total 21 Variables



→ DOE Sensitivity Analysis for Radiation Analysis

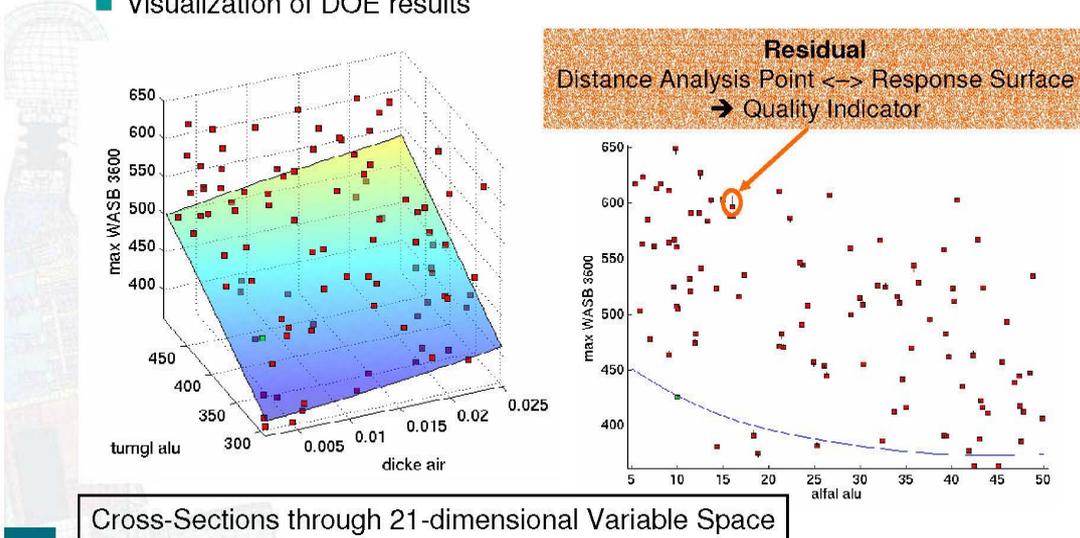
■ Process Flow



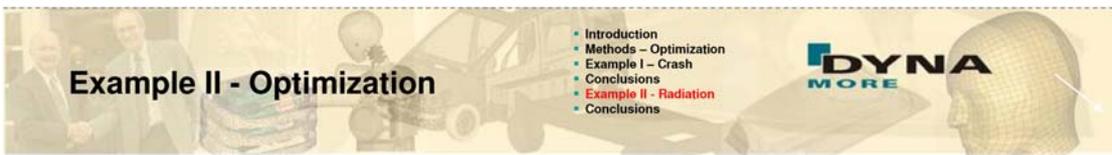


→ DOE Sensitivity Analysis for Radiation Analysis

■ Visualization of DOE results

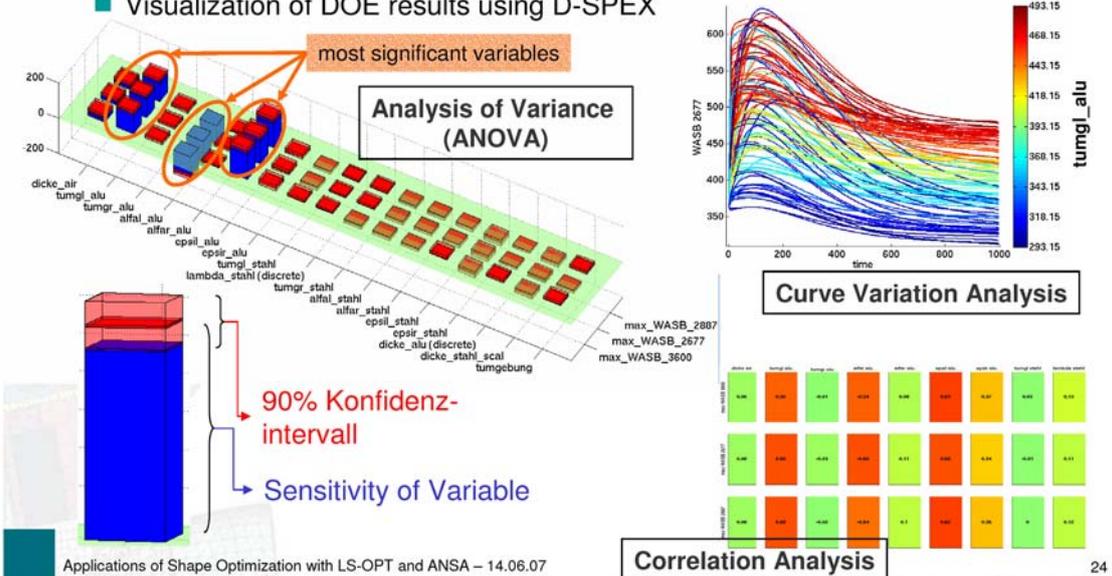


Cross-Sections through 21-dimensional Variable Space



→ DOE Sensitivity Analysis for Radiation Analysis

■ Visualization of DOE results using D-SPEX



Correlation Analysis



## Conclusions

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### → Conclusions

- Meta-Modelling capabilities of LS-OPT are utilized successfully for a sensitivity analysis of a heat radiation problem
- Screening of significant and insignificant variables is performed
- Problem: High dimensional design variable space (21-dim.)
- D-SPEX is a helpful tool to explore the multi-dimensional variable space



Thanks for your attention!

