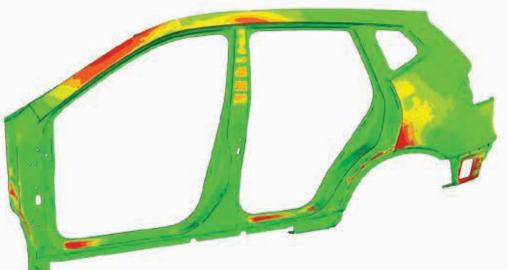
Eliminating physical clamping processes with the aid of Engineering Simulation













# Motevattoiofor a new solution

- Ekapenpisingein general
- Limited repeatability
- Functional problems



#### **Virtual Clamping**

0.75 0.5 0.25 -0.25

-0.5 -0.75 -1

No Value

VCA



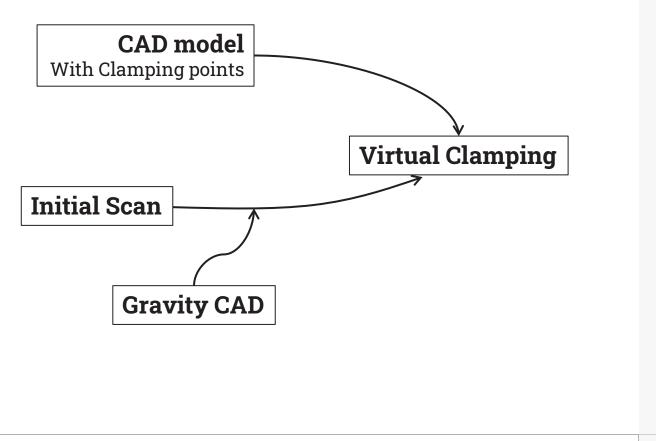


EPILYSIS SOLVER



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#### **VCA Process**

- 1. Imports the designed CAD model
- 2. Imports the scanned model
- 3. Adds loadcase on Scan
- 4. Generate the result

#### VCA Process / 1. Import CAD model

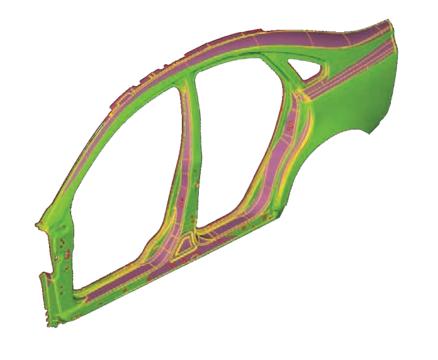
POINT	×
	* Q.D
ið Name	(V) = 1, 1 +
1 PPS 001 (NX2 Point 2 PPS 002 (N2 Point 3 PPS 003 (N2 Point 4 PPS 003 (N2 Point 5 PPS 005 (N2 Point 5 PPS 005 (N2 Point 6 PPS 102 (N2 Point 9 PPS 103 (N2 Point 10 PPS 104 (N2 Point 11 PPS 106 (N2 Point 13 PPS 106 (N2 Point 13 PPS 106 (N2 Point 14 PPS 106 (N2 Point 15 PPS 106 (N2 Point 16 PPS 110 (N2 Point 17 PPS 111 (N2 Point 16 PPS 110 (N2 POINT 16 PPS 110 (N2 POINT 16 PPS 110 (N2 POINT 17 PPS 111 (N2 POINT 17 PPS	
19 RP5_113_fy_Point 20 RP5_114_fy_Point	
21 RPS_115_fy_Point 22 RPS_116_fx_Point	
23 8P5 117 fz Point	1
* 24 RP5 118 fz Point	a a a a a a a a a a a a a a a a a a a
POINT	total 36   selected 0





### Import CAD model

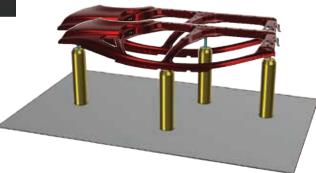
- 3D and skin representation
- Clamping points:
  - Surface
  - Holes



#### **VCA Process**

- 1. Imports the designed CAD model
- 2. Imports the scanned model

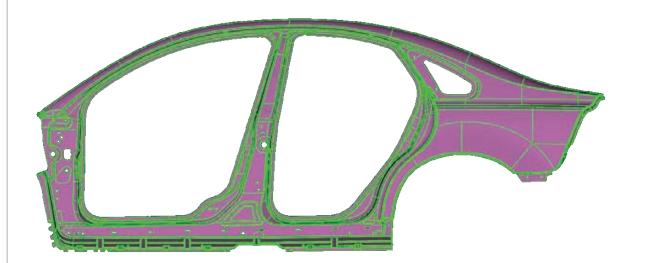




#### **Initial Scan**

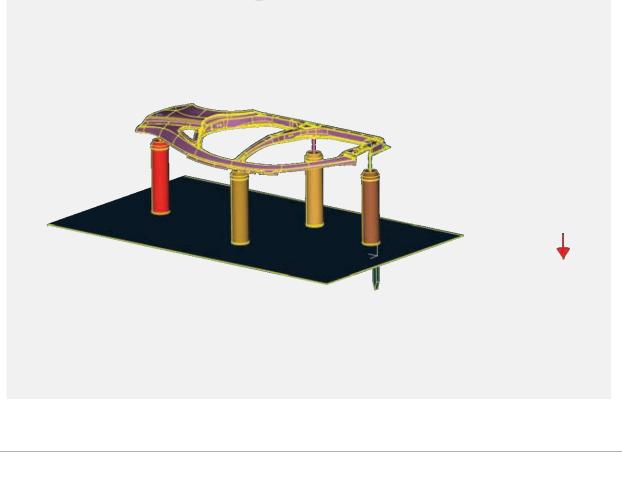
- Scan the part in a "free state"
- Simple adjustable fixture design
- 3 or more mounting points





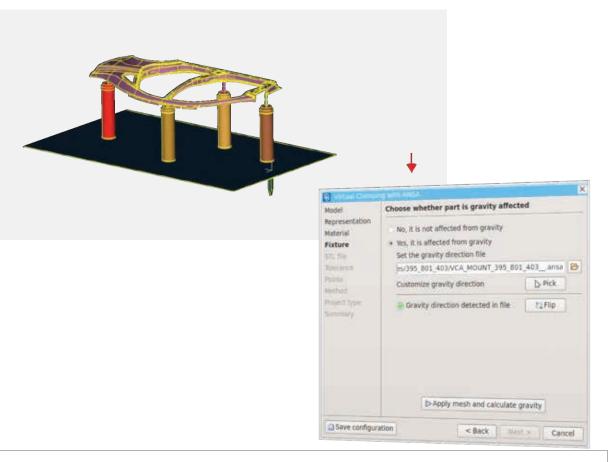
#### Positioning

- STL Positioning using the 3-2-1 scheme
- Projections on the scan
- Methodical process repeatability



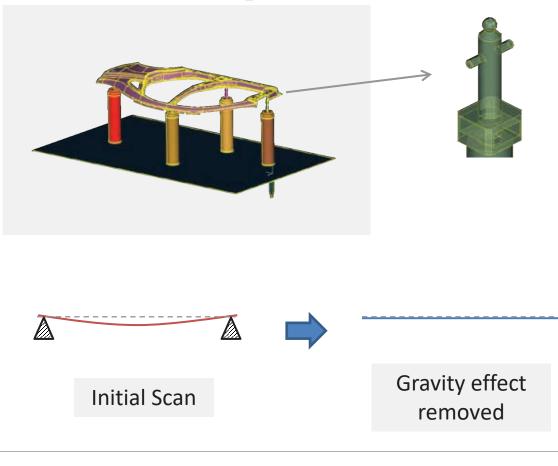
#### **Gravity effect**

- Influence of gravity during scanning
- Import the gravity/scan set-up
- Add loadcase items
- Remove gravity effect from the scan



#### **Gravity effect**

- Influence of gravity during scanning
- Import the gravity/scan set-up
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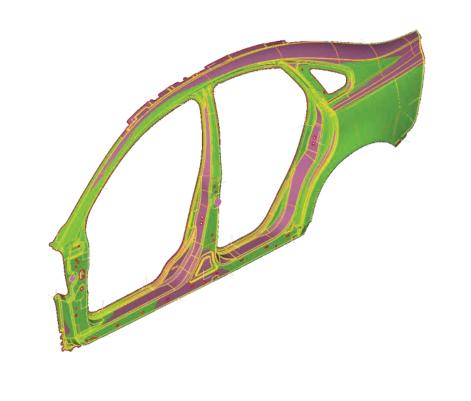
#### **Gravity effect**

- Influence of gravity during scanning
- Import the gravity/scan set-up
- Add loadcase items
- Remove gravity effect from the scan



#### **Symmetry scans**

- Mirrored Scan parts can be used.
- It is specified after the STL input.



#### **VCA Process**

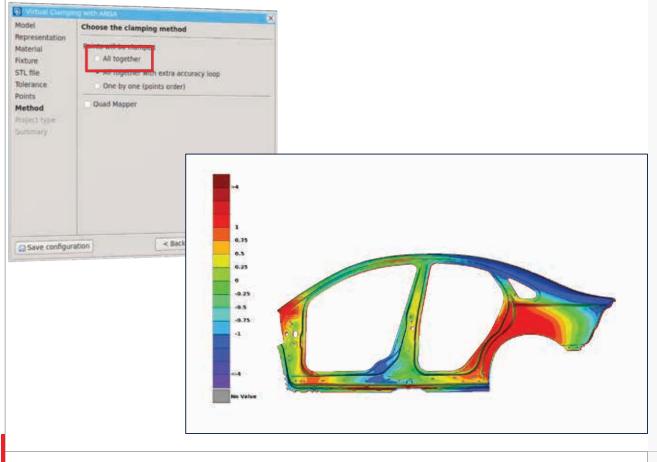
- 1. Imports the designed CAD model
- 2. Imports the scanned model
- 3. Adds loadcase on Scan

Model	Define the source and order for clamping points								
Representation									
Material	Points from the model								
Fixture	<ul> <li>Points from config (.ini) file</li> </ul>								
STL file	Order Point name Color								
Tolerance									
Points	1								
Method	3 V RPS 003 Fy	=							
	4 <b>V</b> RPS 004 Fy								
Project type	5 V RPS 005 Fy								
Summary	6 ✔ RPS 104 fy								
	7 🗹 RPS_105_fy								
	8 🗹 RPS_101_fy								
	9 ✔ RPS_102_fy								
	10 🗹 RPS_103_fy								
	11 🗹 RPS_106_fy								
	12 <b>R</b> PS_107_fy	-							
	13 RPS 108 fv								
	<ol> <li>Clamping points (21/27)</li> </ol>								

#### **Clamping points**

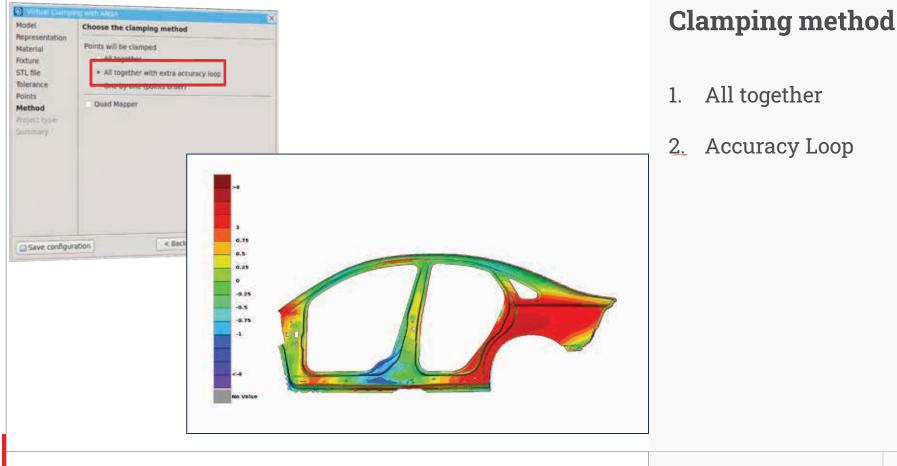
• Change the clamping sequence





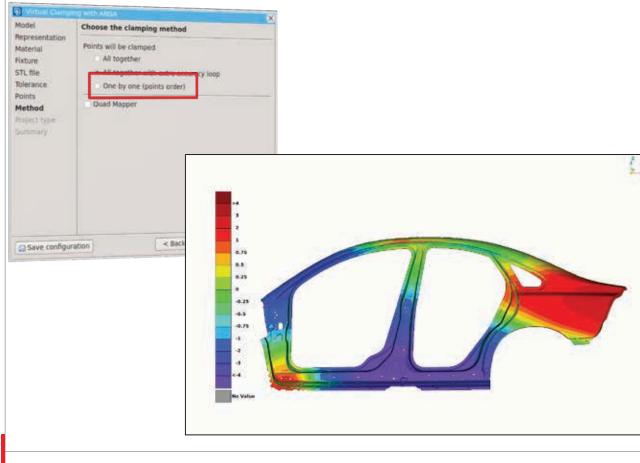
#### **Clamping method**

1. All together



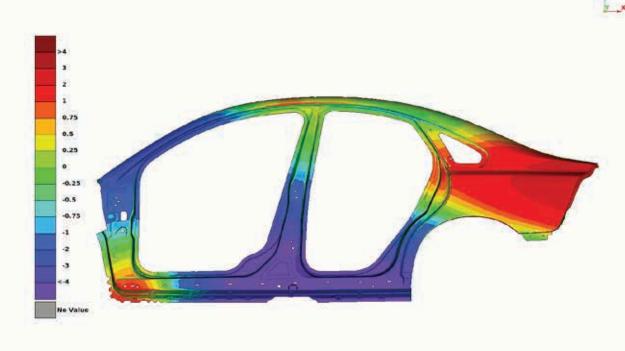
All together





#### **Clamping method**

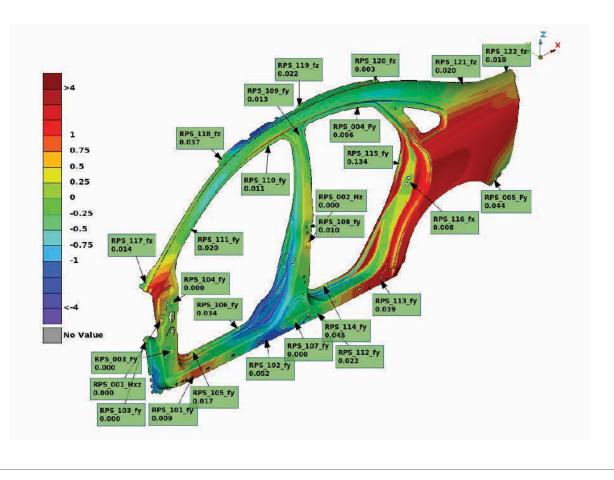
- 1. All together
- 2. Accuracy Loop
- 3. One by one



## Clamping method

- All together
- Accuracy Loop
- One by one



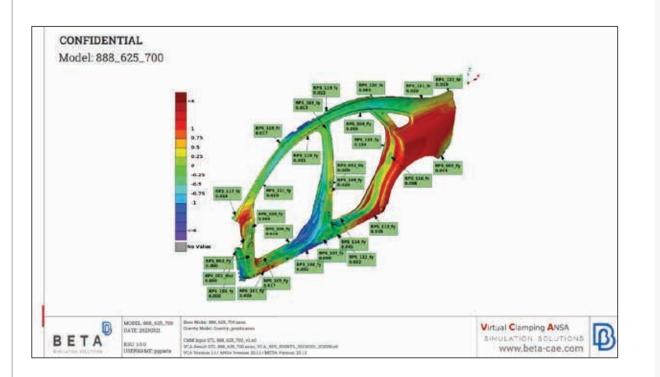


#### **VCA Process**

- 1. Imports the designed CAD model
- 2. Imports the scanned model
- 3. Adds loadcase on Scan
- 4. Generate the result



#### VCA Process / 4. Result



#### Output

- Result STL file(s)
- Comparison PDF file
- Configuration file.

#### VCA Process / 4. Result

RPS Point	Disp X	Disp Y	Disp Z	Disp Total	Force Applied (N) (w common materials)	1000	TIAL /Actual-sol Y   Z   DIAM	lved	TOLERANCE
RP5_001_Hxz	-1.6393	2.7031	-0.5486	3.2086	66.1812 0.3		0.2 -0.2/0.2 -0.2/0.2 -0.2/0.0 0.0		0.0000/-0.4380/-0.0001/0.0000
RPS_002_Hr RPS_003_Fy	-2.3871	4.6022	9.3645	10.7039 4.0954	2.9170		0 2/0 2 -0 2/0 2 -0 2/	0.00.0	0.1624/-0.3467/0.0001/0.0000
	0.1768						0.2 -0.2/0.2 -0.2/0.2	0.2	0.0000/0.0003/0.0000/0.0003
RPS_004_Fy	4.0720	3.6289	17.2152	18.0586	112.0016	02-02/02-02/02-02		0.2	-0.0042/0.0958/-0.0562/0.1111
RPS_005_Fy	-0.5838	12.2266	21.5182	24.7561	1.7716			0.2	0 0142/-0 0444/-0 0005/0 0466
RPS_101_fy	3.0911	3.4524	3.3702	\$.7300	Vertual C	al Clamping with ANSA			
RP5_102_by	3.0801	-1.8602	5.0148	6.1721	Model Representat				default value and the RP
RP5_103_fy	-1.4052	2.3355	-1.1685	2.9656	Material		Default value		0.2
nra_toa,ny	-t.euac	£.5305	-1.1003	\$19000	Fixture STL file		RPS file name	¢sy.	
RPS_104_fy	-2.0505	3.5295	-0.0237	4.0820	Tolerance		LTA file name	CSV.	
2 10	10		40 	005	Points Method		Point name	хvz	
					Project type Summary		Preview tole		ance points is not availab

Save configuration

#### Output

0 0

total 0

Cancel

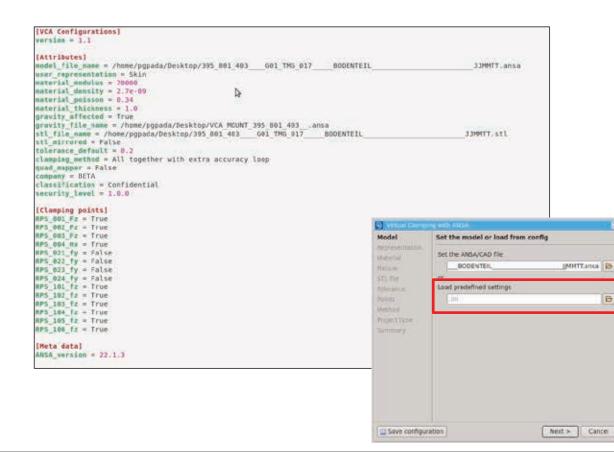
Next >

< Back

- Result STL file(s)
- Comparison PDF file
- Configuration file.



#### VCA Process / 4. Result



#### Details

- A configuration file is automatically saved at the end of the process.
- The user can access the file edit it and reuse it.

- Designed for non-ANSA users
- Reduces expenses for the creation of clamping devices
- One adjustable fixture is needed for all parts
- Reduces set-up time of the scan procedures
- Quick evaluation of additional clamping scenarios
- Works with all scanner devices

VCA Process Benefits

- Addition of Tailored blank parts, with multiple materials and thicknesses
- Assembly of multiple clamped parts
- Optimization of the clamping sequence and positions, to reduce final displacements
- Implementation in Komvos software
- Addition of an external solver for thermal simulations

VCA Process Next Steps



